

Generating Robust Counterfactual Witnesses for Graph Neural Networks

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Equal Contribution



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OVERVIEW

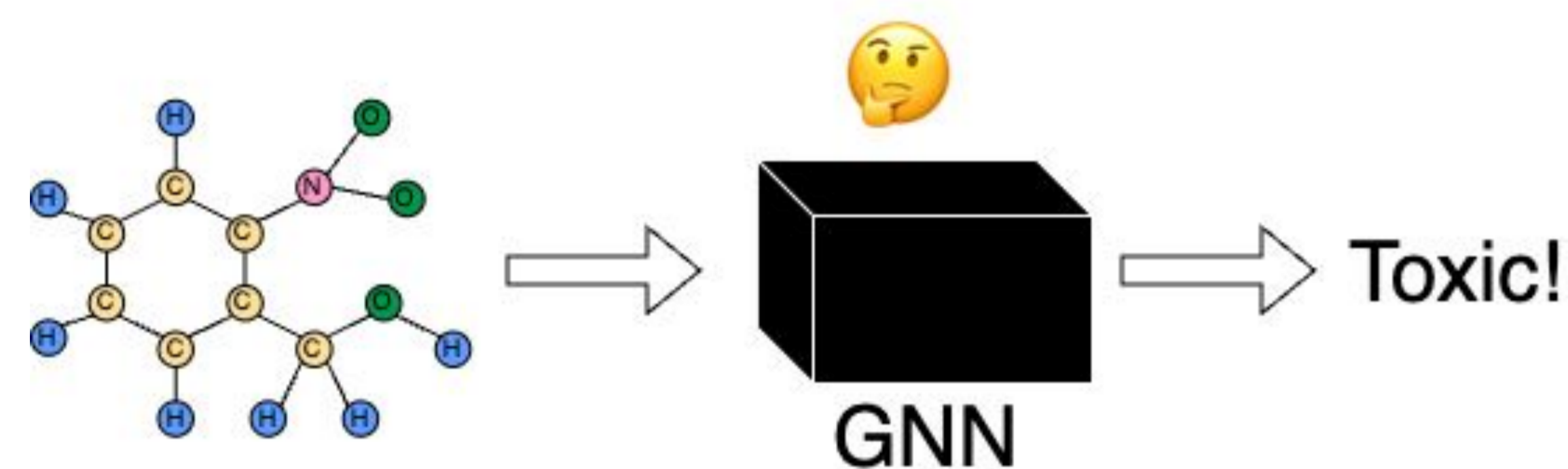
Background/Motivation

“Black-Box” GNNs:

- The inference of GNN models are black-box.
- Hard to understand which part of the input causes the results.

“Explainability”:

- Domain experts requires reliable predictions.
- Highly related to trustworthy challenges.



Explanation Structures

Factual Explanation:

- $M(v, G) = M(v, G_s) = l$

Counterfactual Explanation:

- $M(v, G) \neq M(v, G \setminus G_s) \neq l$

Robust Explanation:

- G_s remains consistent under disturbance.

RCW Verification & Generation Problem

Verification Problem: Given G_s , decide if G_s is a k -RCW for a set of test nodes V_t , w.r.t a model M .

- Witness verification \leftarrow PTIME.
- CW verification \leftarrow PTIME.
- k -RCW verification \leftarrow NP-hard.

Generation Problem: Given a graph G and V_t , compute a k -RCW if exists.

- k -RCW generation in general \leftarrow co-NP-hard
- under (k, b) -disturbances \leftarrow PTIME.

Highlights

All three objectives:

- We are the first to consider all three objectives, i.e., the explanation structure.

Hardness

- Construct PTIME solution for both verification (NP-Hard) and generation problem (co-NP Hard).

Parallel Algorithm

- Proposed parallel version for both verification and generation problem for large graphs.

ALGORITHMS

A1-Verification of Witness

Factual Verification:

- Conduct the model inference to verify if the subgraph is a witness.

Counterfactual Verification:

- Conduct the model inference to verify if the subgraph is a counterfactual witness.

Robust Verification:

- For each “non-true” label (labels \neq prediction), verify if the subgraph remains a CW under k edge flips.
- For each node in the “fragile” area (remaining subgraph), select top- b edges that are most likely changing the node labels. (PageRank score)

A2-Generating k -RCW

Expand:

- Includes node pairs that most likely to change its label if “flipped”.
- Augment the subgraph (initialized with test nodes) with edges that minimize the worst-case margin.

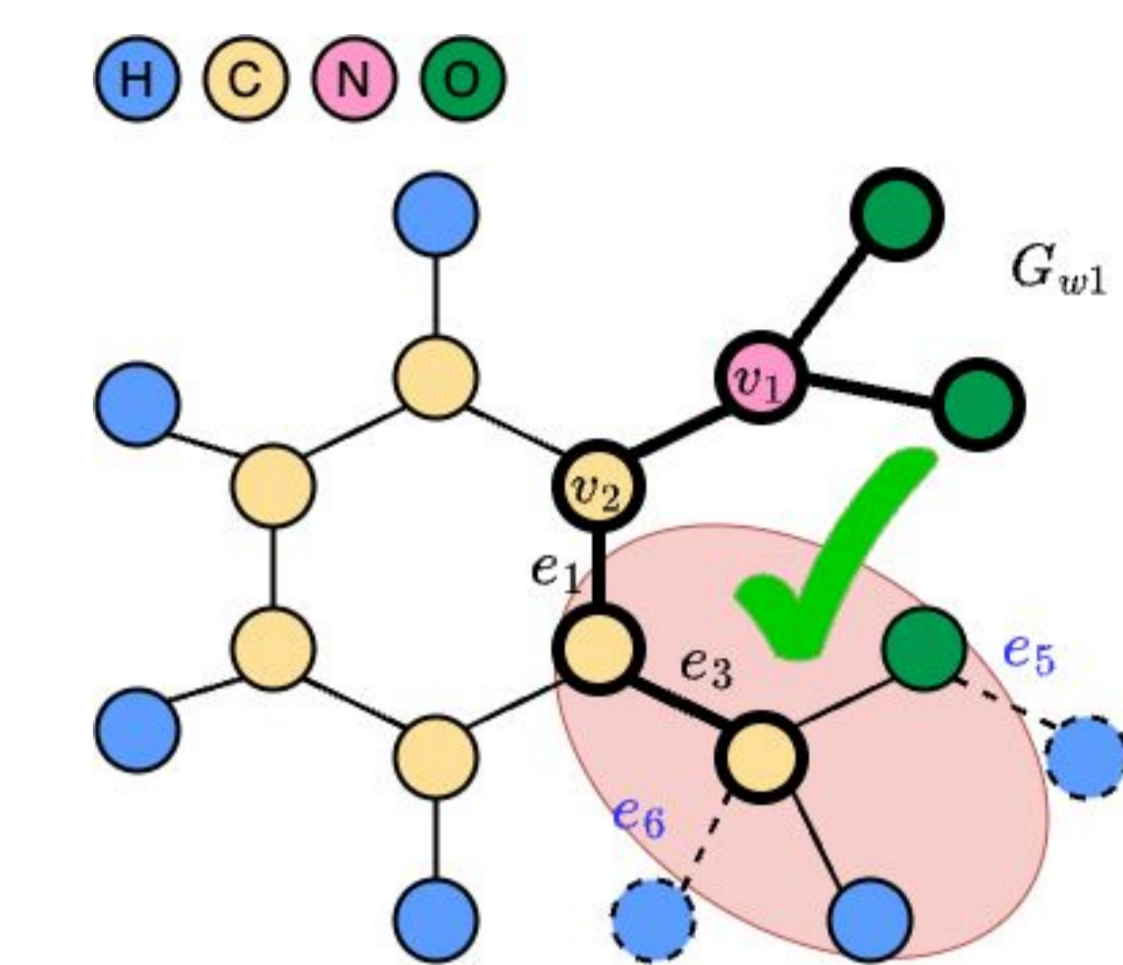
Verify:

- Check if the expanded subgraph is RCW
- Under k -disturbance: k edges that are most likely to change the prediction.

A3-Parallel Generation

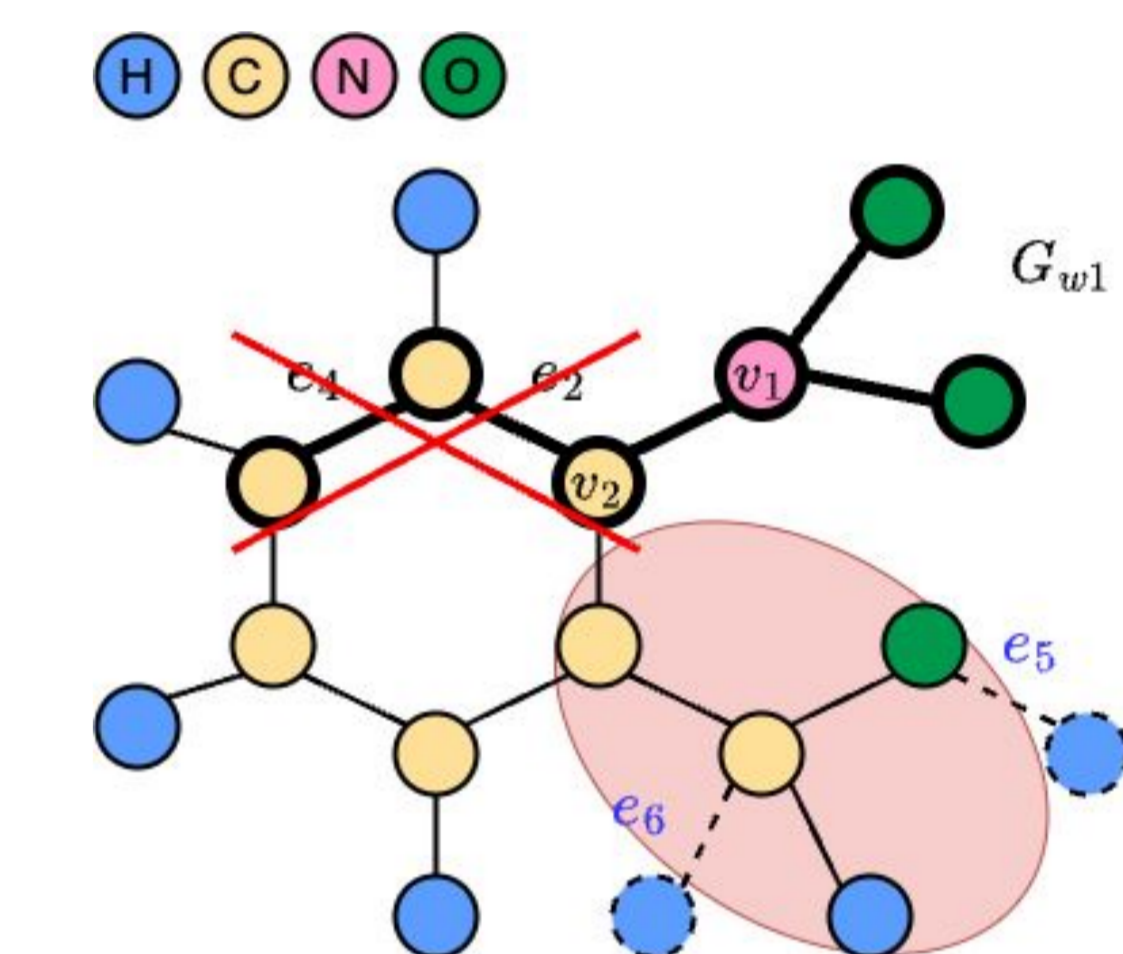
Partition:

- Edge-cut based partition where each worker processes one fragment graph.
- Using a bitmap to record the verified k -disturbance to avoid redundant verification.



Union:

- Assemble a global subgraph from each worker with the local subgraph.
- In each worker expand and verify local subgraph, and maintain the local bitmap.



EXPERIMENTS

Experiment Setting

Datasets

Dataset	# nodes	# edges	# node features	# class labels
BAHouse	300	1500	-	4
PPI	2,245	61,318	50	121
CiteSeer	3,327	9,104	3,703	6
Reddit	232,965	114,615,892	602	41

Baselines

Baselines	Counterfactual	Factual	Robustness
CF-GNNExp (AISTATS 2022)	✓		
CF ² (WWW 2022)	✓	✓	
RoboGExp	✓	✓	✓

Metrics

- Consistency $\text{normalized GED}(G_w, G'_w) = \frac{\text{GED}(G_w, G'_w)}{\max(|G_w|, |G'_w|)}$
- Fidelity+ $\text{Fidelity+} = \frac{1}{|V_T|} \sum_{v \in V_T} (\mathbb{1}(M(v, G) = l) - \mathbb{1}(M(v, G \setminus G_s) = l))$
- Fidelity- $\text{Fidelity-} = \frac{1}{|V_T|} \sum_{v \in V_T} (\mathbb{1}(M(v, G) = l) - \mathbb{1}(M(v, G_s) = l))$

ACKNOWLEDGE

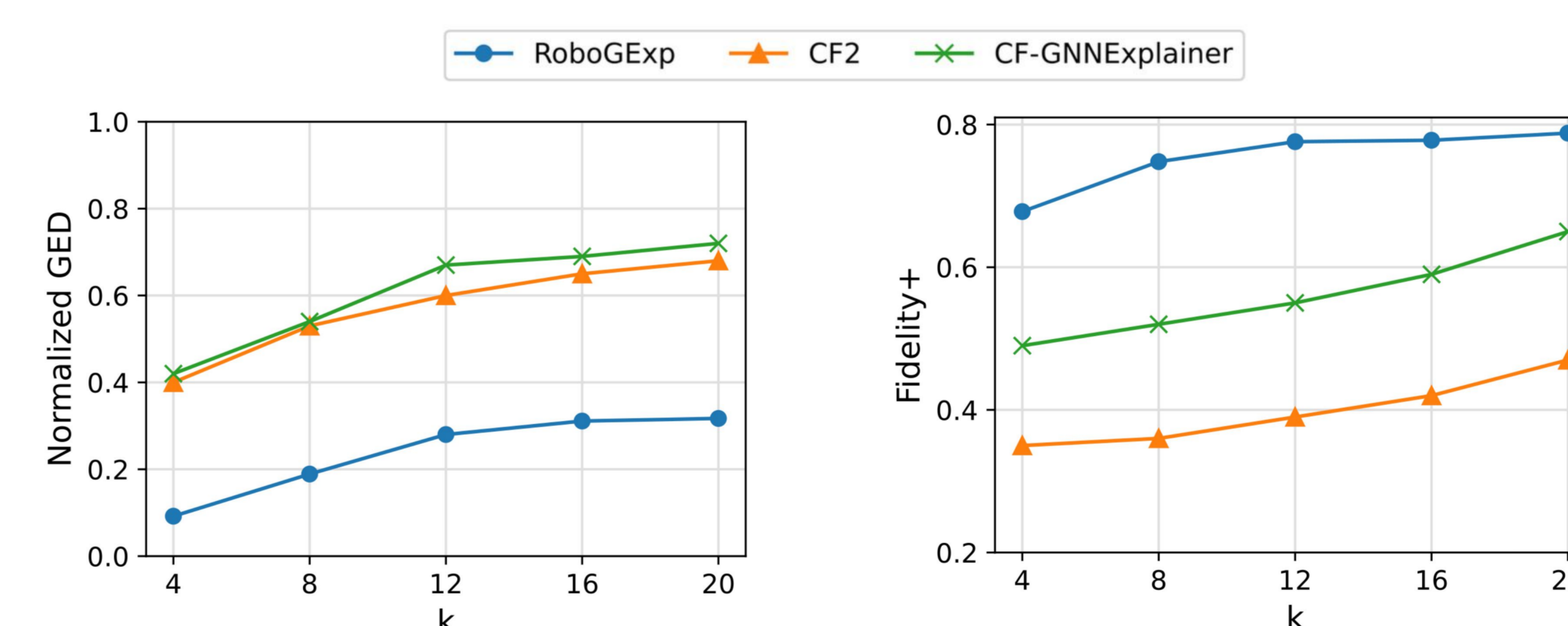
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Experiment Results

Exp1 - Effectiveness: quality of explanations

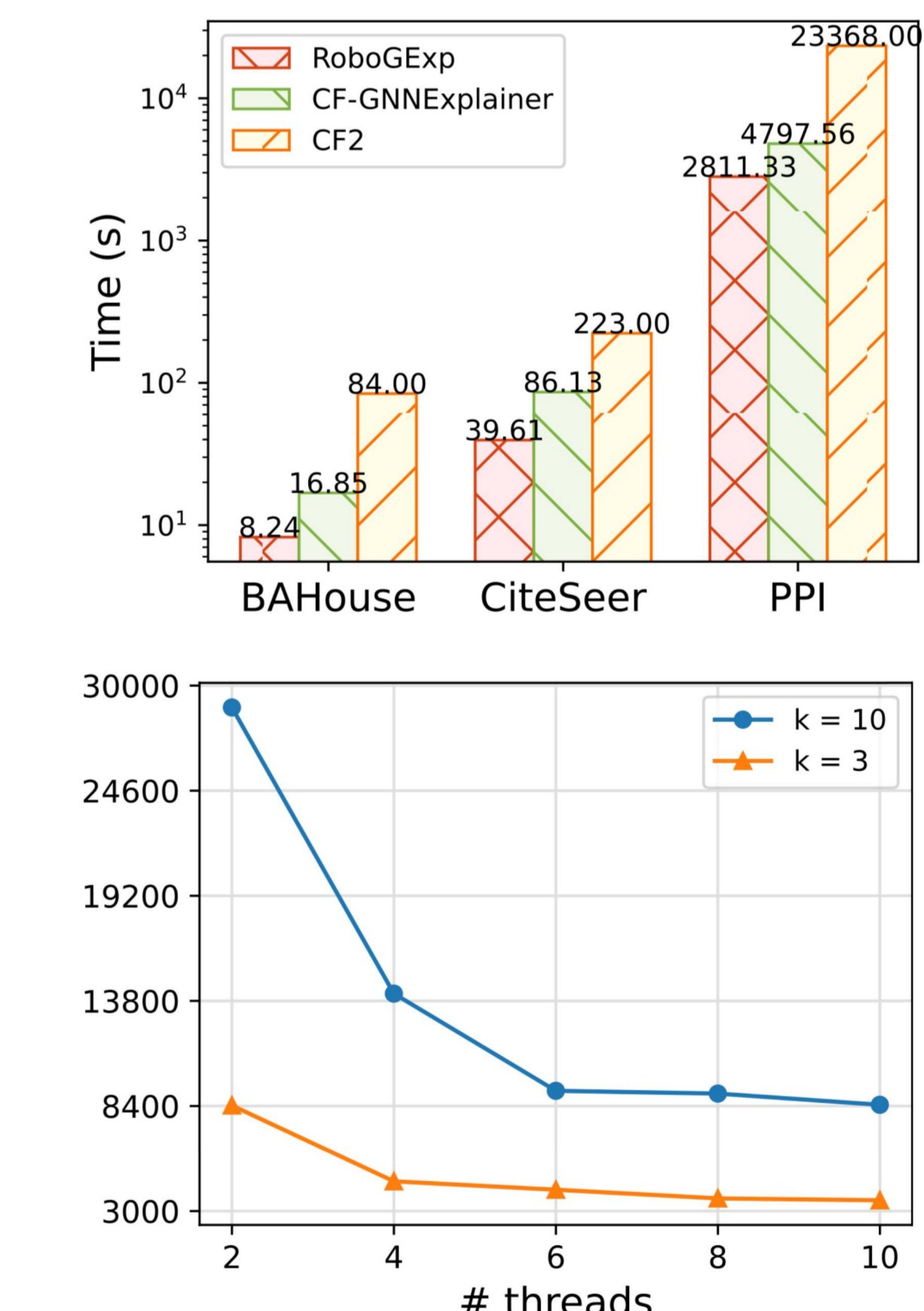
	NormGED	Fidelity+	Fidelity-	Size
RoboGExp	0.32	0.79	0.05	66
CF ²	0.68	0.47	0.06	132
CF-GNNExp	0.72	0.65	0.13	78

Exp2 - Effectiveness: impact of factors



- Robustness facilitates the consistency of the explanation under disturbance.
- Verification ensures good performance under high disturbance.
- Computing a set of nodes and parallelization contributes to the efficiency and scalability.

Exp3 - Efficiency & Scalability



RoboGExp TEAM

